

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	87	382/106,154.ccls. and (project\$4) near4 (light illuminat\$4) and (point fiducial marker) near4 (object) near4 (sensor video camera)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:19
L2	15	((ban near kazunori) (kanno near ichiro)). inv. and three and dimensional and point and measuring and parameter	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:19
L3	99	382/106,154.ccls. and (line) near4 (camera video sensor) near4 (object)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:19
L4	108	382/153.ccls. and (position location) near4 information	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:20
L5	1	(dimensional and two and three and information and combining and determine and position and measuring and space and surface and object and receiving and captured and camera and area and characteristic and point and new and intersection).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:20
S1	215	382/153.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 13:07
S2	1719	382/154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 17:04

S3	6	382/154.ccls. and kosaka.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 14:39
S4	28	("5138667" "5440392" "5531520" "5751843" "5828770" "5832139" "5905806" "5921992" "6013308" "6144761" "6175647" "6222937" "6304680" "6324296" "6363169").PN. OR ("6724930").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/23 14:31
S5	899	382/154.ccls. and projection	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 18:13
S6	156	382/154.ccls. and projection and (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 08:08
S7	128	382/154.ccls. and projection and (marker fiducial) and light\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:08
S8	383916	((OKADA TAKUSHI SUGIMOTO KOICHI SAKAGAMI MUNEYUKI HATA SEIJI).inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:09
S9	735	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEIJI)).inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:09

S10	233	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEIJI)).inv. and (position)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:51
S11	243	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEIJI)).inv. and (position (three near dimensional))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:10
S12	25	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEIJI)).inv. and (position and (three near dimensional))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:10
S13	233	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEIJI)).inv. and (position)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 15:54
S14	2	"20040005092".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:53
S15	617	382/154.ccls. and projection and light\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:53
S16	128	382/154.ccls. and projection and (marker fiducial) and light\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:55
S17	121	382/154.ccls. and projection and (marker fiducial) and light\$4 and ((position location) and (orientat \$4 rotat\$5))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:56

S18	6	382/154.ccls. and kosaka.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/25 19:38
S19	214	382/154.ccls. and robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/25 18:59
S20	66	382/154.ccls. and robot with (position location)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/25 19:00
S21	75	382/154.ccls. and affine near2 transform \$5	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/25 19:38
S22	2	"20030039403".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 08:08
S23	2	"5604819".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 08:32
S24	2	"6128405".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:24
S25	2252	382/106,154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:24
S26	387	382/106,154.ccls. and (project\$4) near4 (light illuminat\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:28
S27	77	382/106,154.ccls. and (project\$4) near4 (light illuminat\$4) and (point fiducial marker) near4 (object) near4 (sensor video camera)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:37

S28	2	"6574361".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:38
S29	2	"6046745".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:38
S30	2	"5699444".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:38
S31	77	382/106,154.ccls. and (project\$4) near4 (light illuminat\$4) and (point fiducial marker) near4 (object) near4 (sensor video camera)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 17:44
S32	122	382/106,154.ccls. and (spot slit) near (light illuminat\$4)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 12:35
S33	86	382/106,154.ccls. and (line) near4 (camera video sensor) near4 (object)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 12:36
S34	268	382/106,154.ccls. and (distance) near4 (camera video sensor) near4 (object)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 16:50
S35	0	382/106,154.ccls. and geometric\$2 near4 (deform\$5) near4 (parameter)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 16:52
S36	24	382/106,154.ccls. and geometric\$2 near4 (deform\$5)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 17:50
S37	2	"20040080758".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 17:50

S38	2	"20040080758".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 23:22
S39	2	"20020097906".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 23:26
S40	507	382/106,154.ccls. and (calculat\$4 comput\$4 determin\$4) near4 (rotat\$4 orient\$5) and reference	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 23:28
S41	154	382/106,154.ccls. and (calculat\$4 comput\$4 determin\$4) near4 (rotat\$4 orient\$5) and reference near (shape image object)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 01:29
S42	2	"5280542".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 02:26
S43	2	"5917940".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 02:52
S44	30	lieu.xa.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 02:53
S45	19	382/153.ccls. and camera near4 mount \$4 near4 robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 02:53
S46	87	382/153.ccls. and (position location) near4 information	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 13:13
S47	46	382/153.ccls. and (position location) near4 information and (camera video sensor) near4 (robot)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 13:14

S48	33	382/153.ccls. and (position location) near4 information and (camera video sensor) near4 (mount\$5)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 13:14
S49	367	382/154.ccls. and calibrat\$4 near3 camera	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/23 13:10
S50	26	382/154.ccls. and calibrat\$4 near3 (camera and (light slit illuminat\$4))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/23 13:22
S51	2	"5280542".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/23 17:34
S52	0	("4926489" "7263216").inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/30 15:49
S53	4	("4926489" "7263216").pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/30 15:49
S54	2	"7263216".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/30 18:48
S55	4	("4926489" "7263216").pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/30 22:56
S56	99	382/106,154.ccls. and (line) near4 (camera video sensor) near4 (object)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:37

S57	85	382/106,154.ccls. and (project\$4) near4 (light illuminat\$4) and (point fiducial marker) near4 (object) near4 (sensor video camera)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:37
S58	134	382/106,154.ccls. and (spot slit) near (light illuminat\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:37
S59	178	382/106,154.ccls. and (calculat\$4 comput\$4 determin\$4) near4 (rotat\$4 orient\$5) and reference near (shape image object)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:37
S60	28	382/154.ccls. and calibrat\$4 near3 (camera and (light slit illuminat\$4))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:37
S61	1	(pattern and light and projecting and surface and straight and line and slit and first and second and rotation and shape and entire and object and entire and part and measuring).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:39
S62	1	(dimensional and two and three and information and combining and determine and position and measuring and space and surface and object and receiving and captured and camera and area and characteristic and point and new and intersection).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:41
S63	126	((ban near kazunori) (kanno near ichiro)). inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:43

S64	79	((ban near kazunori) (kanno near ichiro)). inv. and three and dimensional	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:44
S65	39	((ban near kazunori) (kanno near ichiro)). inv. and three and dimensional and point and measuring	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:44
S66	15	((ban near kazunori) (kanno near ichiro)). inv. and three and dimensional and point and measuring and parameter	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:44
S67	6	((ban near kazunori) (kanno near ichiro)). inv. and three and dimensional and point and measuring and parameter and slit	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/02 12:45

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